## NOTE

## Methods for the Numerical Evaluation of Fourier Integrals ${ }^{1}$

In many problems, Fourier transforms of the form

$$
\begin{equation*}
\Phi(\omega)=\int_{0}^{\infty} f(t) \cos (\omega t) d t \tag{1}
\end{equation*}
$$

must be evaluated numerically. Some methods have been used to treat this problem with limited success [1]-[4]. The method introduced here has also been successfully employed in certain applications [5]. In this method, the domain of integration is partitioned into two regions: $0 \leqslant t \leqslant t_{m}$ and $t_{m} \leqslant t \leqslant \infty$, designated as the near region and asymptotic region, respectively. The Fourier integral can then be written as $\Phi(\omega)=I\left(\omega, t_{m}\right)+J\left(\omega, t_{m}\right)$, where $I$ and $J$ are the near and asymptotic contributions, respectively. The different methods of evaluating the terms $I$ and $J$, are discussed below.

## A. Near Region

Let $\left\{t_{i}\right\}, i=1,2 \cdots m$, be a proper net (subdivision) on the interval $\left\{0, t_{m}\right\}$. Then

$$
\begin{equation*}
I=\sum_{i=1}^{m-1} I_{i}, \quad \text { where } \quad I_{i}=\int_{t_{i}}^{t_{i+1}} f(t) \cos (\omega t) d t \tag{2}
\end{equation*}
$$

Different techniques can be used to approximate the elements $\left\{I_{i}\right\}$. Commonly, $f(t)$ is approximated in the interval $\left(t_{i}, t_{i+1}\right)$ by a simple function whose product with $\cos (\omega t)$ is readily integrable in closed form. Hastrup [4] has used a linear function, and Filon [1] has used a quadratic. Since $f(t)$ must be monotonedecreasing over much of its domain, the behavior of such functions can often be better approximated by simple exponentials over limited regions. Thus, one may write $f(t) \cong g(t)=\alpha_{i} \exp \left(\beta_{i} t\right)$ for $\left(t_{i} \leqslant t \leqslant t_{i+1}\right)$ where the values of the parameters $\alpha_{i}$ and $\beta_{i}$ are fixed by the conditions $g(t)=f(t)$ at $t=t_{i}$ and $t_{i+1}$. The exponential approximation yields

$$
\begin{align*}
I_{i}= & \frac{\alpha_{i}}{\beta_{i}{ }^{2}+\omega^{2}}\left\{e^{\beta_{i} t_{i+1}\left[\beta_{i} \cos \left(\omega t_{i+1}\right)+\omega \sin \left(\omega t_{i+1}\right)\right]}\right. \\
& \left.\left.-e^{\beta_{i} t_{i}\left[\beta_{i}\right.} \cos \left(\omega t_{i}\right)+\omega \sin \left(\omega t_{i}\right)\right]\right\} . \tag{3}
\end{align*}
$$

[^0]For slowly varying $f(t)$, an alternative approach employs the law of the mean. Applying the mean-value theorem to Eq. (2), one can write

$$
\begin{equation*}
I_{i}=f(\bar{t}) \int_{t_{i}}^{t_{i+1}} \cos (\omega t) d t=\frac{f(\bar{t})}{\omega}\left[\sin \left(\omega t_{i+1}\right)-\sin \left(\omega t_{i}\right)\right] \tag{4}
\end{equation*}
$$

where $\bar{t}$ is some value of $t$ in the interval ( $t_{i}, t_{i+1}$ ). Application of the mean-value theorem implies that the zeros of $\cos (\omega t)$ must be a subset of $\left\{t_{i}\right\}$. The two simplest approximations for slowly varying $f(t)$ are $f(\bar{t}) \cong f\left[\frac{1}{2}\left(t_{i}+t_{i+1}\right)\right]$ or $f(\bar{t}) \cong$ $\frac{1}{2}\left[f\left(t_{i}\right)+f\left(t_{i+1}\right)\right]$.

In many experimental applications, $f(t)$ is not measured directly. Instead, the integral of $f(t)$ over an interval in $t$ is observed. [Consider the example where $f(t)$ represents the count-rate function of some detection system. The total count recorded during any time interval is then the integral of $f(t)$ over that interval.] In such applications, where $f(t)$ does not change sign, it is appropriate to employ the law of the mean in a different way. One may write

$$
\begin{equation*}
I_{i}=\cos \left(\omega \bar{t}_{i}\right) \cdot F_{i}, \quad \text { where } \quad F_{i}=\int_{t_{i}}^{t_{i+1}} f(t) d t \tag{5}
\end{equation*}
$$

Here $\bar{t}_{i}$ again represents some value of $t$ in $\left(t_{i}, t_{i+1}\right)$, and $F_{i}$ is an experimental datum. If the set of experimental data $\left\{F_{i}\right\}$ does not cover the entire range of $t$, then gaps must be filled in by interpolation.

## B. Asymptotic Region

The asymptotic contribution, $J\left(\omega, t_{m}\right)$, depends essentially upon the behavior of $f(t)$. In this region, $t_{m}$ is chosen large enough so that a simple asymptotic representation of $f(t)$ is valid for all $t \geqslant t_{m}$. If $f_{\text {gs }}(t)$ denotes this asymptotic representation, then $J_{\mathrm{ap}}(\omega, t)$, the approximate asymptotic contribution, is

$$
\begin{equation*}
J\left(\omega, t_{m}\right) \cong J_{\mathrm{ap}}\left(\omega, t_{m}\right)=\int_{t_{m}}^{\infty} f_{\mathrm{as}}(t) \cos (\omega t) d t, \quad\left(t \geqslant t_{m}\right) \tag{6}
\end{equation*}
$$

With $t_{m}$ sufficiently large, $J_{\mathrm{ap}}\left(\omega, t_{m}\right)$ can be evaluated by expansion in an asymptotic series (i.e., in terms of inverse powers of $t_{m}$ ), giving to $n$th order

$$
\begin{equation*}
J_{\mathrm{ap}}\left(\omega, t_{m}\right)=\sum_{k=1}^{n} \frac{a_{k}\left(\omega, t_{m}\right)}{t_{m}{ }^{k}} . \tag{7}
\end{equation*}
$$

It is usually necessary to retain only a few terms. The coefficients $\left\{a_{k}\right\}$ often contain sine and cosine terms, so that by propitious choice of $t_{m}$ the leading-term coefficient $a_{1}$ can be made to vanish.

There exists another series expansion which may be useful between the near and asymptotic regions. Let $\left\{t_{\nu}\right\}$ represent the zeros of $\cos \{\omega t)$ in this intermediate region. Then the intermediate-region contribution, $K\left(\omega, t_{0}\right)$, is

$$
\begin{equation*}
K\left(\omega, t_{0}\right)=\sum_{v=1}^{N} A_{2 v+1}, \quad \text { where } \quad A_{2 \nu+1}=\int_{t_{2 v}}^{t_{2 v+2}} f(t) \cos (\omega t) d t . \tag{8}
\end{equation*}
$$

Using the Taylor-series expansion of $f(t)$ about $t=t_{2 v+1}$ in Eq. (8), one finds

$$
\begin{equation*}
A_{2 v+1}=\mp(1 / \omega) \sum_{n=0}^{\infty} \frac{f^{(2 n+1)}\left(t_{2 \nu+1}\right)}{(2 n+1)!}(1 / \omega)^{2 n+1} \int_{-\pi}^{\pi} x^{2 n+1} \sin x d x \tag{9}
\end{equation*}
$$

where the $(-)$ or $(+)$ sign applies if the principal value of $\left(\omega t_{2 v+1}\right)$ is $\frac{1}{2} \pi$ or $\frac{3}{2} \pi$, respectively. One finds for the first few terms

$$
\begin{align*}
A_{2 v+1}= & \mp(1 / \omega)\left[(2 \pi / \omega) f^{(1)}\left(t_{2 v+1}\right)+\frac{\pi\left(\pi^{2}-6\right)}{3 \omega^{3}} f^{(3)}\left(t_{2 v+1}\right)\right. \\
& \left.+\frac{\pi\left(\pi^{4}-20 \pi^{2}+120\right)}{60 \omega^{5}} f^{(5)}\left(t_{2 v+1}\right)+\cdots\right] . \tag{10}
\end{align*}
$$

For $f(t)$ slowly varying compared to $\cos (\omega t)$, the higher-order terms will decrease quite rapidly. This expansion may be useful in the asymptotic region. Here, calculations should be carried out until $K\left(\omega, t_{0}\right)=J_{\mathrm{ap}}\left(\omega, t_{0}\right)$ is independent of $N$.
Accuracy can be estimated using the fact that $\Phi(\omega)$ should be independent of $t_{m}$, provided the asymptotic expansions are valid. Moreover, since $t_{m}$ can be chosen sufficiently large, one can always satisfy the condition, $|I| \gg\left|J_{\mathrm{ap}}\right|$. Hence, the asymptotic term can be used to estimate that value of $t_{m}$ for which $I$ approximates $\Phi(\omega)$ to a specified degree of accuracy. The asymptotic term can also provide an estimate for the remainder of the infinite alternating series considered by Hurwitz and Zweifel [3]. One need no longer be concerned with the convergence properties of such series, because the calculation in the near region can be terminated as soon as a desired accuracy has been attained. This procedure can be quite effective in many applications where comparison with experiment requires a knowledge of Fourier transforms to only a few percent.

## C. Example

Numerical results have been obtained for the Fourier integral [5]

$$
\begin{equation*}
\Phi(\omega)=\frac{2 e^{-\alpha}}{\pi} \int_{0}^{\infty} \cos [(\omega-1) t] e^{\beta^{2} t^{2}} \exp \left\{\alpha e^{-\beta^{2} t^{2}} \cos t\right\} \cos \left\{\alpha e^{-\beta^{2} t^{2}} \sin t\right\} d t, \tag{11}
\end{equation*}
$$

where $a$ and $\beta$ are parameters. For the near-region contribution, Eq. (4) was used. The asymptotic contribution for this case is to third order

$$
\begin{equation*}
J_{\mathrm{ap}}\left(\omega, t_{m}\right)=-(-1)^{n}\left[\frac{2 e^{-\alpha}}{\pi}\right] \frac{(\omega-1) \exp \left(-\beta^{2} t_{m}{ }^{2}\right)}{\left(4 \beta^{4} t_{m}^{2}\right)} \tag{12}
\end{equation*}
$$

for values of $t_{m}$ which satisfy $(\omega-1) t_{m}=\left(n+\frac{1}{2}\right) \pi$, with $n$ an integer. Figure 1 , which displays the resulting Fourier transform obtained for the parameter values


Fig. 1. The Fourier transform of

$$
f(t)=\left(2 e^{-\alpha / \pi}\right) \exp \left(-\beta^{2} t^{2}\right) \exp \left[\alpha \exp \left(-\beta^{2} t^{2}\right) \cos t\right] \times \cos \left[\alpha \exp \left(-\beta^{2} t^{2}\right) \sin t\right]
$$

for $\alpha=0.01$ and $\beta=0.06$ in the region $\omega \geqslant 1.6$.
$\alpha=0.01$ and $\beta=0.06$, demonstrates the general utility of this method. Here a relative accuracy of better than $2 \%$ in the value of $\Phi(\omega)$ has been maintained over a domain of about six decades.

## References

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